

Parallel Graph Algorithms in CSCAPES

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CSCAPES Overview

- Institute for Combinatorial Scientific Computing and Petascale Simulations which started at 2006 and funded by DOE/SciDAC
- The development, analysis, and application of combinatorial algorithms to enable scientific and engineering computations (CSC) on extremescale architectures
- The participants:
 - Purdue University: Alex Pothen (Lead PI)
 - Sandia National Laboratories: Erik Boman
 - Ohio State University: Ümit V. Çatalyürek
 - Argonne National Laboratory: Paul Hovland
 - Colorado State: Michelle Mills Strout
 - Totally 11 investigators, 6 postdocs and 8 students.

- The combinatorial problem tackled in CSCAPES:
 - Partitioning, Load Balancing, and Ordering
 - Automatic Differentiation
 - Graph Coloring in Scientific Computing
 - Matching
 - Performance Improvement via Runtime Reordering
 - Multi-scale Algorithms

The scales: sequential, shared memory, clusters, 100K cores



Zoltan

- Zoltan is one of the many software in CSCAPES projects
- A software toolkit for load balancing and parallel data management which is a C library that uses MPI but with bindings for Fortran and C++

Static and dynamic Load Balancing

Using Hypergraph repartitioning algorithms reducing communication and data migration



Graph Coloring

Grouping a set of objects into few independent subsets

- Sparse derivative matrix computations
- Concurrency discovery in parallel computing





Hypergraph Partitioning

• Multilevel Hypergraph Partitioning Algorithm: V-cycle



Initial Partitioning

- **Coarsening**: Iterative matching of highly connected vertices
- Initial Partitioning: Partitioning of the coarsest graph
- **Uncoarsening**: Back projection of coarsest graph to upper level, while improving the quality of partition at each iteration
- Zoltan features a distributed Hypergraph partitioner that scales to thousands of processors
- Currently implementing hybrid hypergraph partitioner to scale to 100K processors



Coloring and its applications

- Graph coloring is an abstraction for partitioning a set of binary-related objects into few "independent sets"
- Major application areas:
 - Sparse derivative matrix computation
 - Concurrency discovery in parallel computing
 - Adaptive mesh refinement
 - Iterative methods for sparse linear systems
 - Full sparse tiling







- Exploit features of initial data distribution
 - Distinguish between interior and boundary vertices
- Proceed in rounds, each having two phases:
 - Tentative coloring
 - Conflict detection
- Coloring phase organized in supersteps
 - A processor communicates only after coloring a subset of its assigned vertices
 - → infrequent, coarse-grain communication



Parallel Graph Coloring





Scalability of Coloring

• Scalability of small graphs on 64 multicore nodes



Bad scalability when more than 1 process per node

But 8 procs per node results show that it is not a memory contention

The problem is software contention on the communication subsystem





- Zoltan is being rewritten as Zoltan 2 in C++ to provide better data type abstraction (e.g., 64 bit integers)
- Currently, Zoltan uses distributed programming.
- Simple partitioning and coordinate-based partitioning currently scale to 200K processors
- Moving toward hybrid programming for better scalability for Hypergraph partitioning and graph coloring



Thanks

- For more information visit
 - http://cscapes.org
 - http://bmi.osu.edu/hpc
- Research at the HPC Lab is funded by

