### Overview of ORNL Leadership Computing Facility and Usage



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Oak Ridge National Laboratory

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## Oak Ridge Leadership Computing Facility Mission

- The OLCF is a DOE Office of Science National User Facility whose mission is to enable breakthrough science by:
- Fielding the most powerful capability computers for scientific research,
- Building the required infrastructure to facilitate user access to these computers,
- Selecting a few time-sensitive problems of national importance that can take advantage of these systems,
- And partnering with these teams to deliver breakthrough science.







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# **Breakthrough Science at Every Scale**

#### **Nuclear Physics**

Nazarewicz et al., map the nuclear driplines that mark the borders of nuclear existence, predicting ~7000 bound nuclei, though only ~3000 have been observed. Nature 2012



#### **New Materials**

Lopez-Bezanilla et al., discover that boron-nitride monolayers are an ideal dielectric substrate for future nanoelectronic devices constructed with graphene as the active layer



#### **Biofuels**

Smith et al., reveal the surface structure of lignin clumps down to 1 angstrom





**Design Innovation** Ramgen Power Systems accelerates their design of shock wave turbo compressors for carbon capture and sequestration

#### Biochemistry

Ivanov et al., illuminate how DNA replication continues past a damaged site so a lesion can be repaired later

#### Turbo Machinery Efficiency

General Electric, for the first time, simulated unsteady flow in turbo machinery, opening new opportunities for design innovation and efficiency improvements.





# We have increased system performance by 1,000 times since 2004

Hardware scaled from single-core through dual-core to quad-core and dual-socket , 12-core SMP nodes

- NNSA and DoD have funded much of the basic system architecture research
  - Cray XT based on Sandia Red Storm
  - IBM BG designed with Livermore
  - Cray X1 designed in collaboration with DoD

Scaling applications and system software is the biggest challenge

- DOE SciDAC and NSF PetaApps programs are funding scalable application work, advancing many apps
- DOE-SC and NSF have funded much of the library and applied math as well as tools
- Computational Liaisons key to using deployed systems



# Hierarchical Parallelism

- Parallelism on multiple levels
  - MPI parallelism between nodes (or PGAS)
  - On-node, SMP-like parallelism via threads
  - Vector parallelism
    - SSE/AVX on CPUs
    - GPU threaded parallelism
- It doesn't matter if you use GPU-based machines or not
  - GPUs [CUDA, OpenCL, directives]
  - FPUs on Power [xlf, etc.]
  - Cell [SPE]

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- SSE/AVX; MIC (Knights Ferry, Knights Corner)[?]

Increasing node-level parallelism and data locality are universally needed





# **ORNL's "Titan" System**

Upgrade of Jaguar from Cray XT5 to XK6

	Titan Specs	
	Compute Nodes	18,688
	Cores (CPU)	299,008
	Login & I/O Nodes	512
)	Memory per node	32 GB + 6 GB
Α	# of Fermi chips (2012)	960
, ,	# of NVIDIA "Kepler" (2013)	14,592
	Total System Memory	688 TB
	Total System Peak Performance	20+ Petaflops
	Cross Section Bandwidths	X=14.4 TB/s Y=11.3 TB/s Z=24.0 TB/s

- AMD Opteron 6274 processors (Interlagos)
- New accelerated node design using NVIDIA
   multi-core accelerators
  - 2011: 960 NVIDIA x2090 "Fermi" GPUs
  - 2012: 14,592 NVIDIA "Kepler" GPUs
- Gemini interconnect
  - 3-D Torus, Globally addressable memory
  - Advanced synchronization features

20+ PFlops peak system performance | 600 TB DDR3 + 88 TB GDDR5 mem



# Cray XK6 Compute Node

#### XK6 Compute Node Characteristics

AMD Opteron 6200 "Interlagos" 16 core processor @ 2.2GHz

Tesla M2090 "Fermi" @ 665 GF with 6GB GDDR5 memory

> Host Memory, 32GB 1600 MHz DDR3

Gemini High Speed Interconnect

Upgradeable to NVIDIA's next generation "Kepler" processor in 2012

Four compute nodes per XK6 blade. 24 blades per rack





# In principle, GPUs are easy

- Identify opportunities for acceleration (loops/high flops)
  - Allocate arrays on GPU
  - Move data from host to GPU
  - Launch computer kernel on GPU
  - Move results from GPU to host
  - Deallocate arrays on GPUs







# • Optimization problem!

- Exploiting strengths (FLOPS), avoiding weakness (DATA MOVEMENT)
- Identifying acceleration opportunities is not obvious
  - New algorithm
    - Minimize data, flops

       *→* minimize data movement
    - Multiple levels of parallelism
  - Revisit good coding practices and vector parallelism





# **Titan (GPU) programming tools** (for now)

Compiler Directives (OpenACC)			Low-level GPU Languages			
Cray	Cray PGI HMPP Toolkit* (CAPS)		OpenCL (agnostic)	CUDA C (NVIDIA)	CUDA Fortran (PGI)	

Intended for portability (GPU, MIC, APU, etc.)

OpenACC: Standard for directives to designate areas for GPU kernels

\* OpenCL/CUDA converted source provided

Accelerated Libraries**							
Libsci_acc (Cray)	MAGMA (ICL/UT) (GNU)	CULA (EM Photonics)	cuBLAS/ cuSparse (NVIDIA)	Trilinos	Etc, etc.		

#### \*\* Libraries are based on CUDA

Pei	Debuggers					
CrayPAT / Vampir / Apprentice VampirTrace	TAU	HPCToolkit	CUDA Profiler	Allinea DDT	NVIDIA	gdb



### **CAAR @ the OLCF** Center for Accelerated Application Readiness

• Titan System Goals: Promote application development for highly scalable architectures

Using six representative apps to explore techniques to effectively use highly scalable architectures

#### CAM-SE

Community Atmospheric Model

#### Denovo

• 3D neutron transport for nuclear reactors

#### wl-LSMS

• First principles statistical mechanics of magnetic materials

#### S3D

Turbulent Combustion model

#### LAMMPS

Molecular Dynamics

#### NRDF

Adaptive mesh refinement

#### Addressing:

- Data locality
- Explicit data management
- Hierarchical parallelism
- Exposing more parallelism through code refactoring and source code directives
- Highly parallel I/O
- Heterogeneous multicore processor architecture



### GPUs on Scalable Applications OLCF-3 Early Science Codes

#### Current performance (ratio) measurements on TitanDev (XK6) vs. XE6

Application	XK6 (w/ GPU) vs. XK6 (w/o GPU)	XK6 (w/ GPU) vs. XE6	Comment
S3D	1.5	1.4	<ul> <li>Hybrid MPI/OpenMP/OpenACC</li> <li>Redesign message passing – overlap</li> <li>6% of Jaguar workload</li> </ul>
Denovo	3.5	3.3	<ul> <li>SWEEP kernel rewritten in C++ &amp; CUDA</li> <li>2% of Jaguar workload</li> </ul>
	6.5	3.2	<ul> <li>Builds with either OpenCL or CUDA</li> <li>1% of Jaguar workload</li> </ul>
WL-LSMS 👹	3.1	1.6	<ul> <li>Accelerated linear algebra libraries</li> <li>2% of Jaguar workload</li> <li>2009 Gordon Bell Winner</li> </ul>
CAM-SE	2.6	1.5	<ul> <li>Hybrid MPI/OpenMP/CUDA</li> <li>1% of Jaguar workload</li> </ul>

Cray XK6: Fermi GPU plus Interlagos CPU; Cray XE6: Dual Interlagos and no GPU



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Current performance (ratio) measurements on TitanDev (XK6) vs. XE6

Application	XK6 (w/ GPU) vs. XK6 (w/o GPU)	XK6 (w/ GPU) vs. XE6	Comment
NAMD	2.6	1.4	<ul> <li>High-performance molecular dynamics</li> <li>2% of Jaguar workload</li> </ul>
Chroma	8.8	6.1	<ul> <li>High-energy nuclear physics</li> <li>2% of Jaguar workload</li> </ul>
QMCPACK	3.8	3.0	<ul><li>Electronic structure of materials</li><li>New to OLCF, Common to</li></ul>
SPECFEM-3D	4.7	2.5	<ul><li>Seismology</li><li>2008 Gordon Bell Finalist</li></ul>
GTC	2.5	1.6	<ul> <li>Plasma physics for fusion-energy</li> <li>2% of Jaguar workload</li> </ul>
СР2К	2.8	1.5	<ul> <li>Chemical physics</li> <li>1% of Jaguar workload</li> </ul>

Cray XK6: Fermi GPU plus Interlagos CPU; Cray XE6: Dual Interlagos and no GPU



# **Two Phase Upgrade Process**

- Phase 1: XT5 to XK6 without GPUs
  - Remove all XT5 nodes and replace with XK6 and XIO nodes
  - 16-core processors, 32 GB/node, Gemini
  - 960 nodes (10 cabinets) have NVIDIA Fermi GPUs
  - Users ran on half of system while other half was upgraded
- Add NVIDIA Kepler GPUs
  - Cabinet Mechanical and Electrical upgrades
    - New air plenum bolts on to cabinet to support air flow needed by GPUs
    - Larger fan

- Additional power supply
- New doors 🙂
- Rolling upgrade of node boards
  - Pull board, add 4 Kepler GPUs modules, replace board, test, repeat 3,647 times!
  - Keep most of the system available for users during upgrade





Image courtesy of Cray Inc.



## Access to Titan

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### **Provide access to LCFs:** More than 2.7 billion core hours awarded in 2012



INCITE Webinar: http://www.doeleadershipcomputing.org/faqs



### **OLCF Allocation Programs** Selecting applications of national importance

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	60% INCITE		30% ALCC		10% Director's Discretionary	
Mission	High-risk, high-payoff science that requires <u>LCF-scale</u> <u>resources*</u>		High-risk, high-payoff science aligned with DOE mission		Strategic LCF goals	
Call	1x/year – (Closes June)		1x/year – (Closes February)		Rolling	
Duration	1-3 years, yearly renewal		1 year		3m,6m,1 year	
Typical Size	30 - 4010M - 100Mprojectscore-hours/yr.		5 - 10 projects	1M – 75M core-hours/yr.	100s of projects	10K – 1M core-hours
Review Process	Scientific Peer-Review	Computational Readiness	Scientific Peer-Review	Computational Readiness	Strategic in feasibility	npact and
Managed By	INCITE management committee (ALCF & OLCF)		DOE Office of Science		LCF management	
Availability	Open to all scientific researchers and organization Capability >20% of cores				nizations	i



# **OLCF User Demographics**



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# **Leadership Metric & Scheduling**

- As a DOE Leadership Computing Facility, the OLCF has a mandate to be used for large, leadership-class (aka capability) jobs.
- To that end, the OLCF implements queue policies that enable large jobs to run in a timely fashion.

Bin	Min Cores	Max Cores	Max Walltime (hours)	Aging Boost (Days)
5	180,000		24.0	15
4	60,000	179,999	24.0	5
3	5,008	59,999	12.0	0
2	2,004	5,007	6.0	0
1	1	2,003	2.0	0

Leadership Usage Metric:

35% of the CPU time used on the system will be accumulated by jobs using 20% or more of the available processors (60,000 cores)

www.olcf.ornl.gov/support/user-guides-policies/jaguar-xk6-user-guide



# The OLCF



# **OLCF Training Programs**

# • 2012

- January:

- February:

- Titan Workshop
- Electronic Structure Calculation Methods on Accelerators
- March: Performance Analysis Tools
- April: OLCF Spring Training & User's Meeting
- May: GPU Technology Conference, San Jose
- June: Crash Course in Supercomputing
- June August: HPC Fundamentals Series Summer
- October 9: Cray technical Workshop on XK6 Programming
- <u>www.olcf.ornl.gov</u> | <u>help@nccs.gov</u>
- Presentations, webinars available

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## Questions

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