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**Barcelona
Supercomputing
Center**

Centro Nacional de Supercomputación

BSC Tools update

Using clustering and Folding

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CScADS – Snowbird, June 2012

Outline

« Computation Structure detection

- Short intro
- Aggregative Refinement
- Tracking program evolution
- Scaling clustering algorithm

« Instantaneous performance metric

- Clustering + Folding

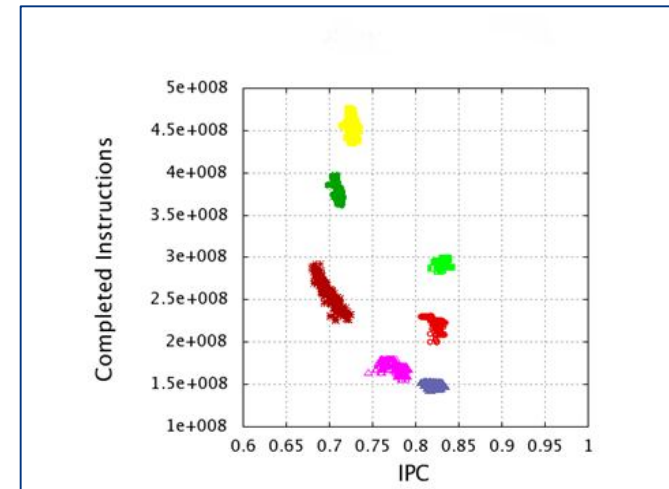
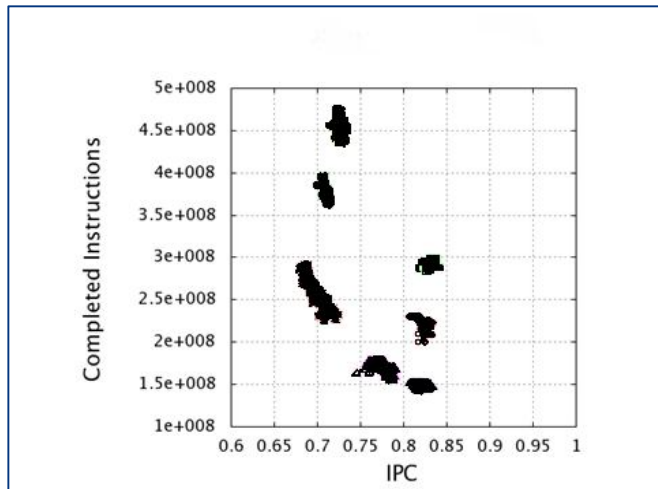
Clustering

Identification of computation structure

- CPU burst = region between consecutive runtime calls
 - Described with performance hardware counters
 - Associated with call stack data

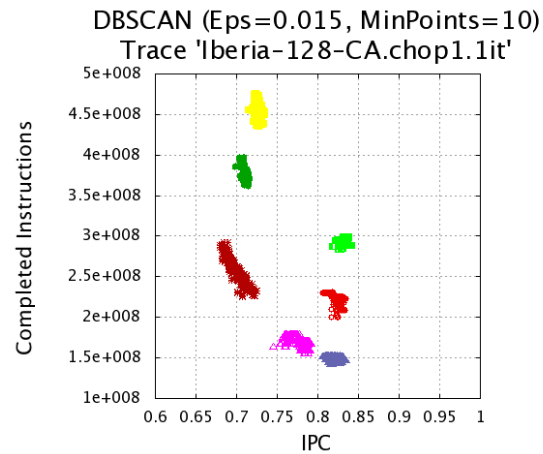
Using DBSCAN density-cluster algorithm

- Data not necessarily Gaussian

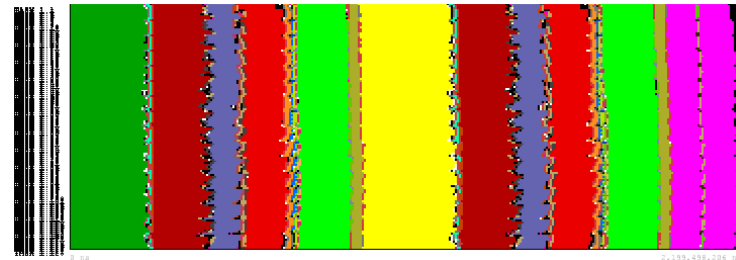


Outputs

Scatter Plot of Clustering Metrics



Clusters Distribution Along Time



Cluster Statistics

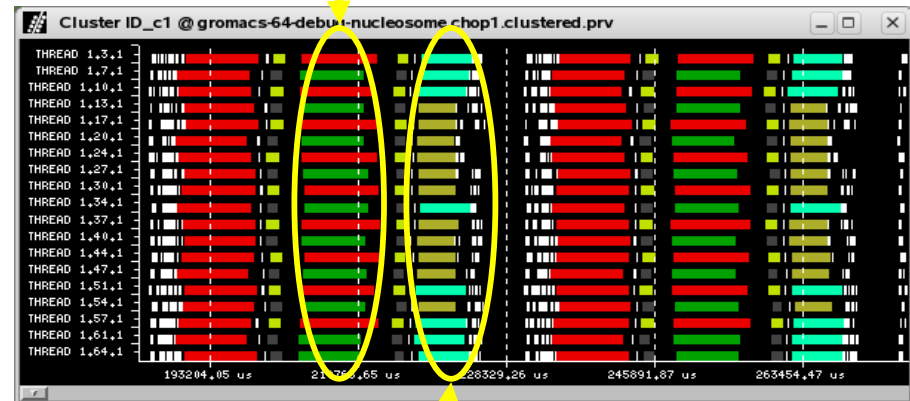
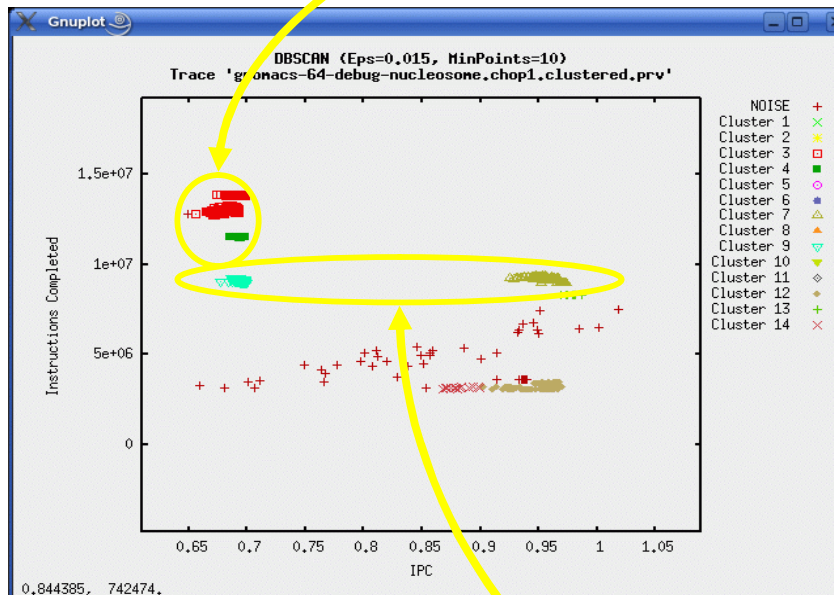
CLUSTER	1	2	3	4	5	6
% TIME	36.29	29.52	10.13	9.68	3.73	1.71
AVG. BURST DUR. (MS)	220.46	177.70	60.81	29.09	38.71	44.83
IPC	0.53	0.50	0.62	0.77	0.66	0.59
MIPS	1210.07	1164.36	1403.19	1743.32	1499.47	1338.24
L1M/KINSTR	22.72	32.63	12.65	8.39	16.12	6.86
L2M/KINSTR	0.59	1.23	1.08	0.61	1.23	1.73
MEM.BW (MB/s)	90.77	182.65	193.32	136.33	236.15	295.71

Code Linking

CLUSTER	CODE SECTION
1	solve_nmm.f:[2037 - 2310]
2	solve_nmm.f:[1478 - 1782] solve_nmm.f:[2030 - 1782]
3	solve_nmm.f:[1241 - 1345]
4	solve_nmm.f:[2771 - 2865] solve_nmm.f:[2388 - 2489]
5	solve_nmm.f:[1478 - 1569]
6	solve_nmm.f:[1607 - 1633]

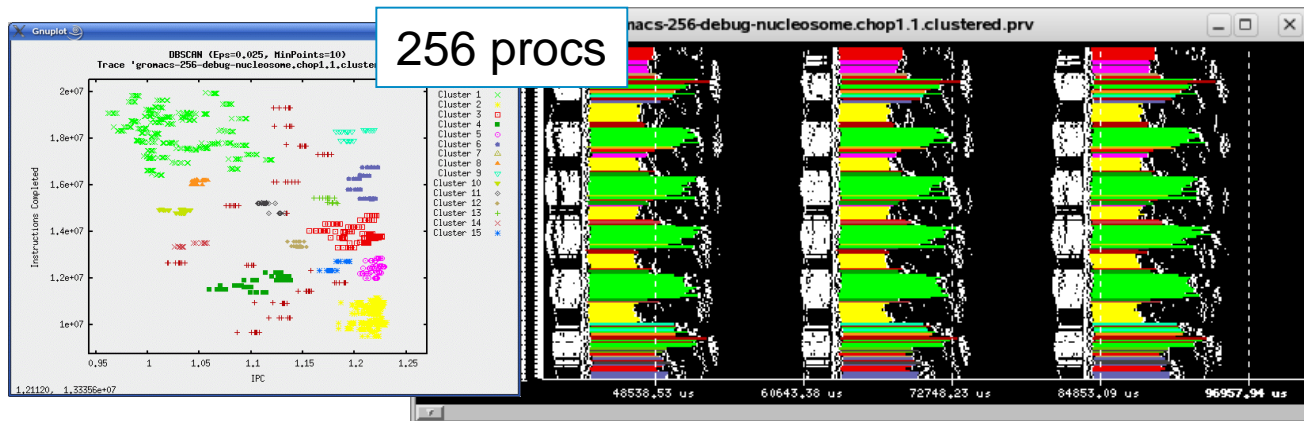
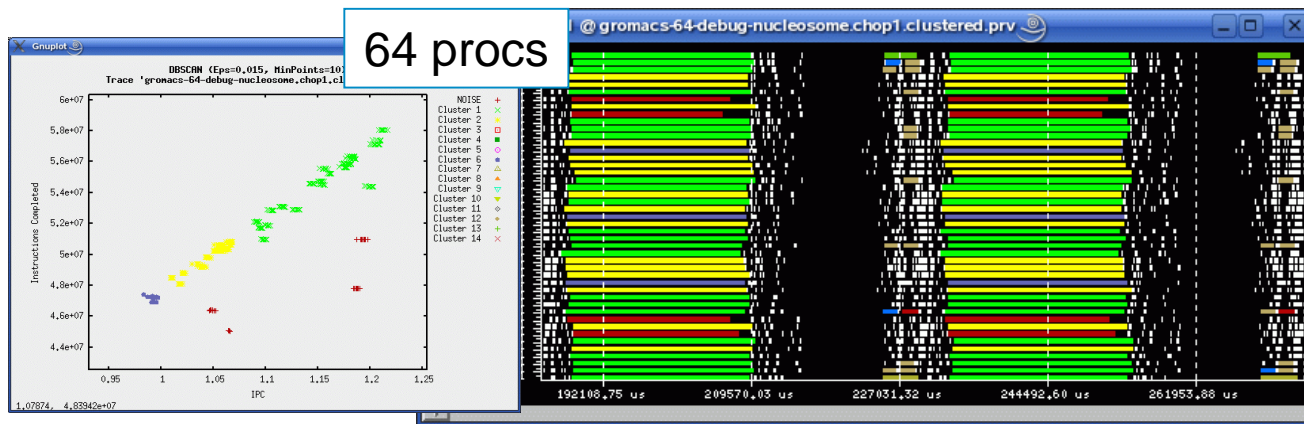
Using clusters to understand apps behavior (GROMACS)

Instructions imbalance



IPC Imbalance

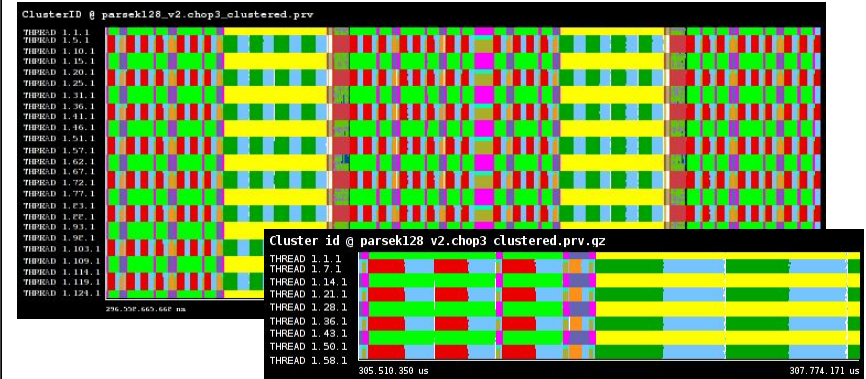
Using clusters to understand apps behavior (GROMACS)



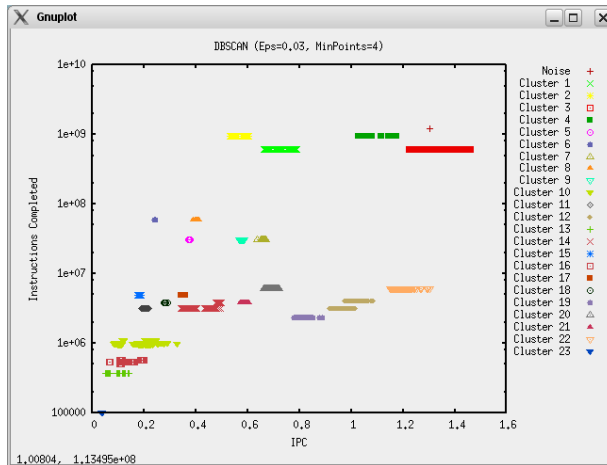
Identifying main code regions (PARSEK)



duration vs. cluster



instr. vs. cluster



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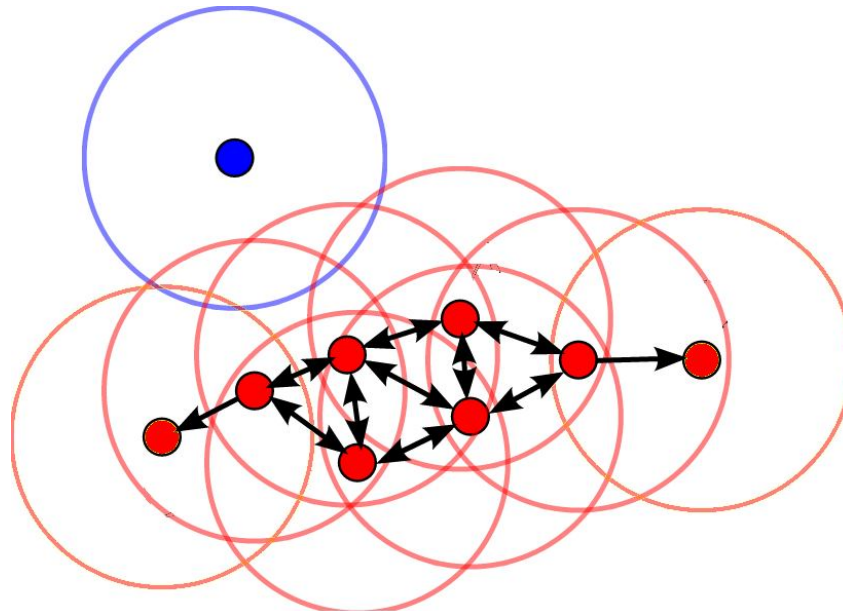
⌋ Instantaneous performance metric

- Clustering + Folding

DBSCAN characteristics

Two parameters

- Epsilon: search radius
- MinPoints: minimum cluster density



Noise point

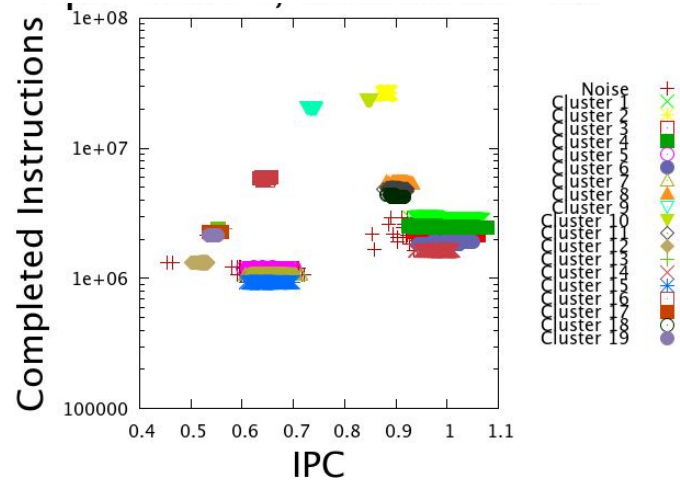


Cluster points

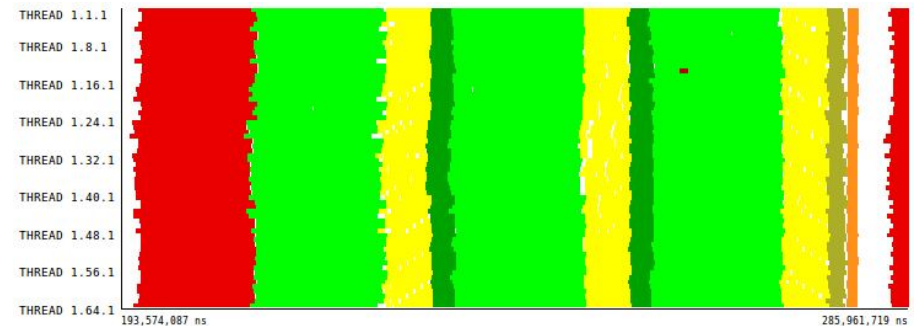
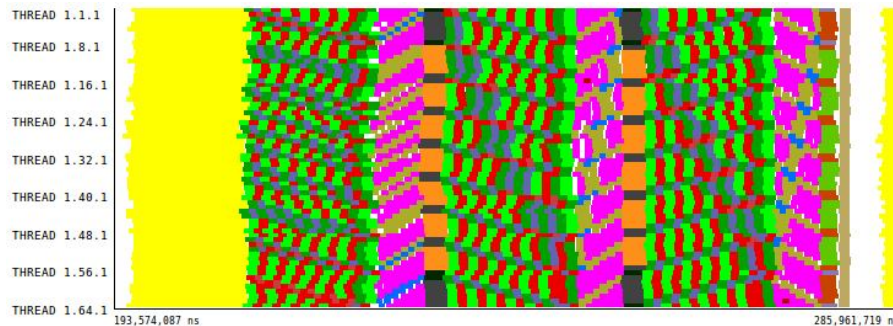
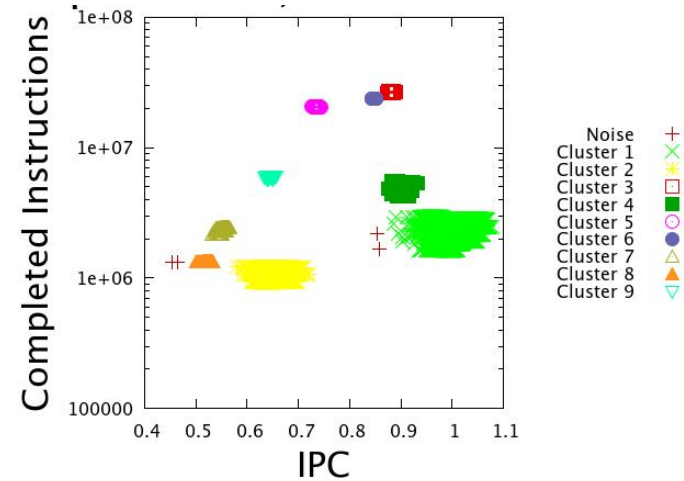
DBSCAN *Eps* selection

Which results are better?

Eps=0.0140 (Low Value)

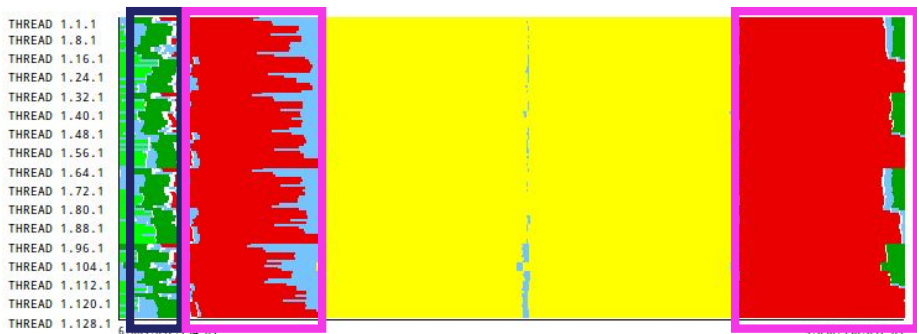
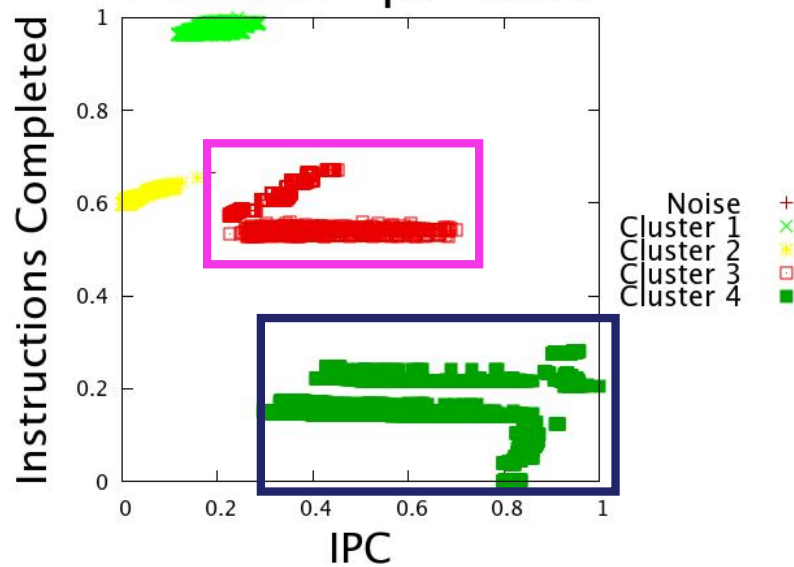


Eps=0.0400 (High Value)

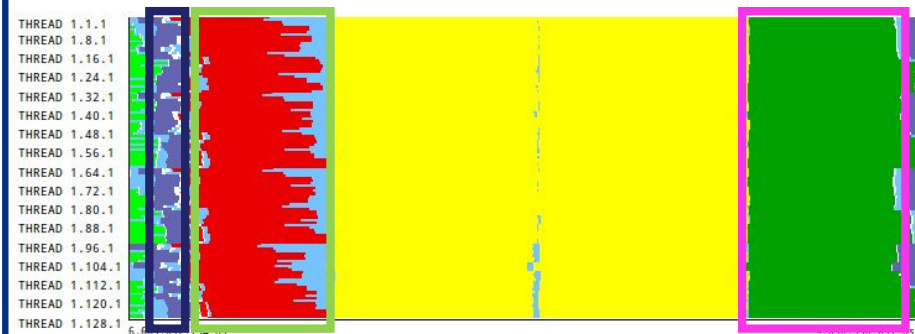
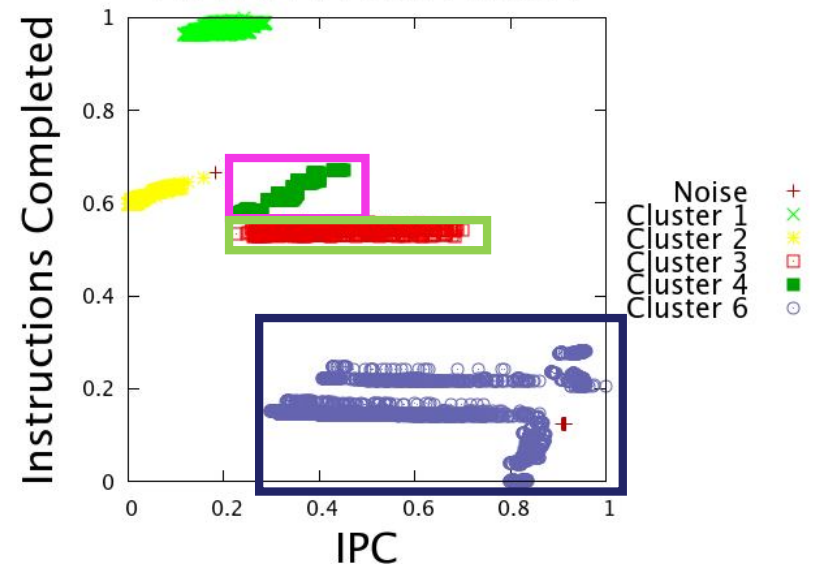


DBSCAN single *Eps* limitation

DBSCAN *Eps*=0.05

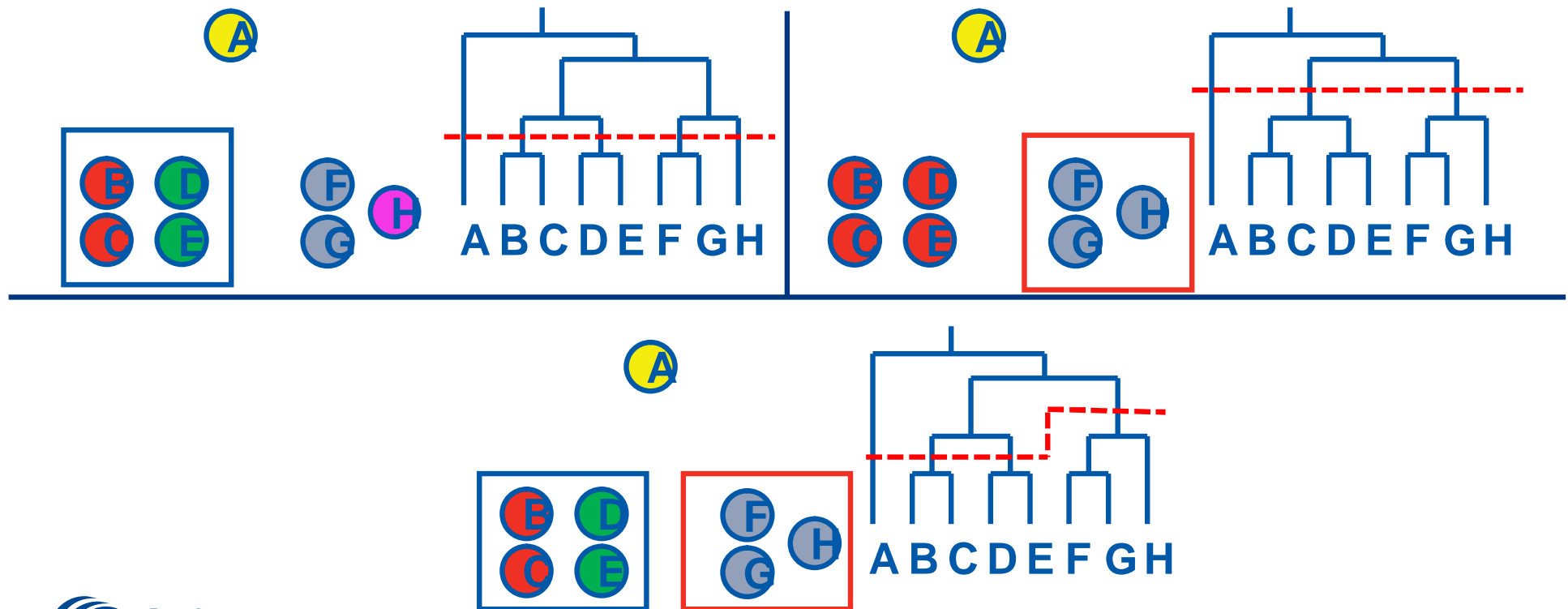


Desired results

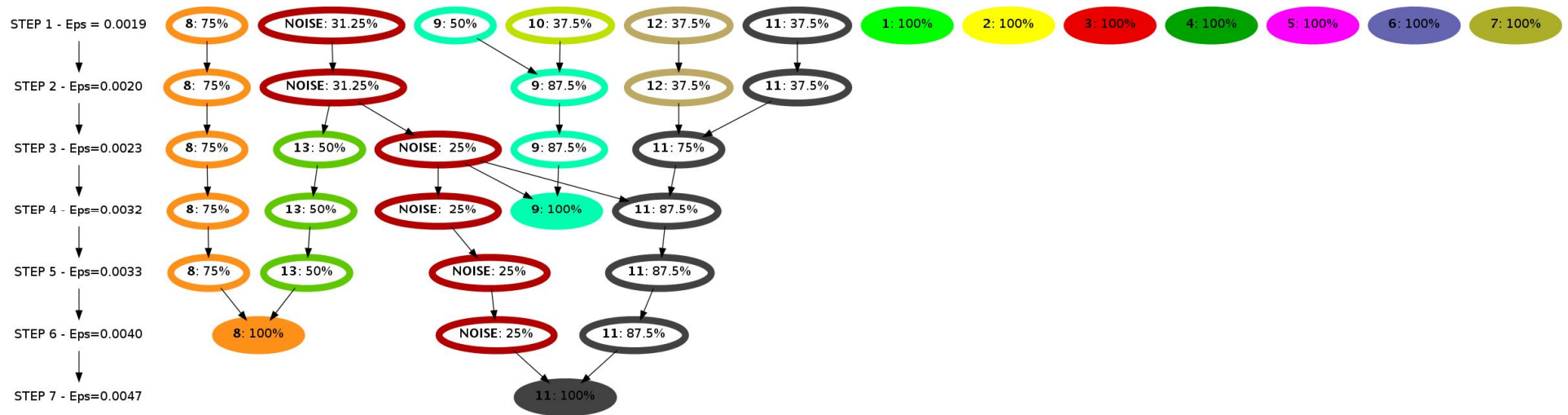
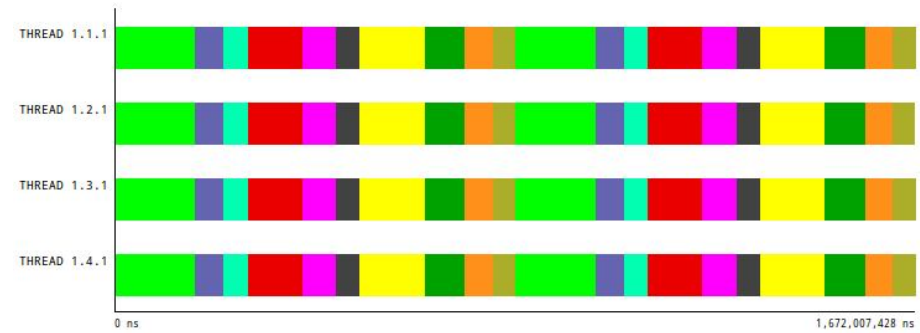
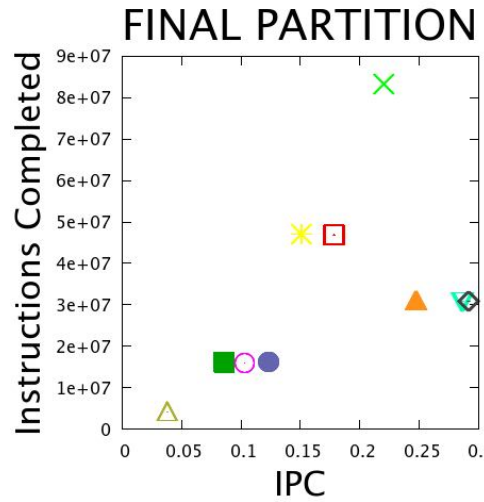


Refinement Algorithm Approach

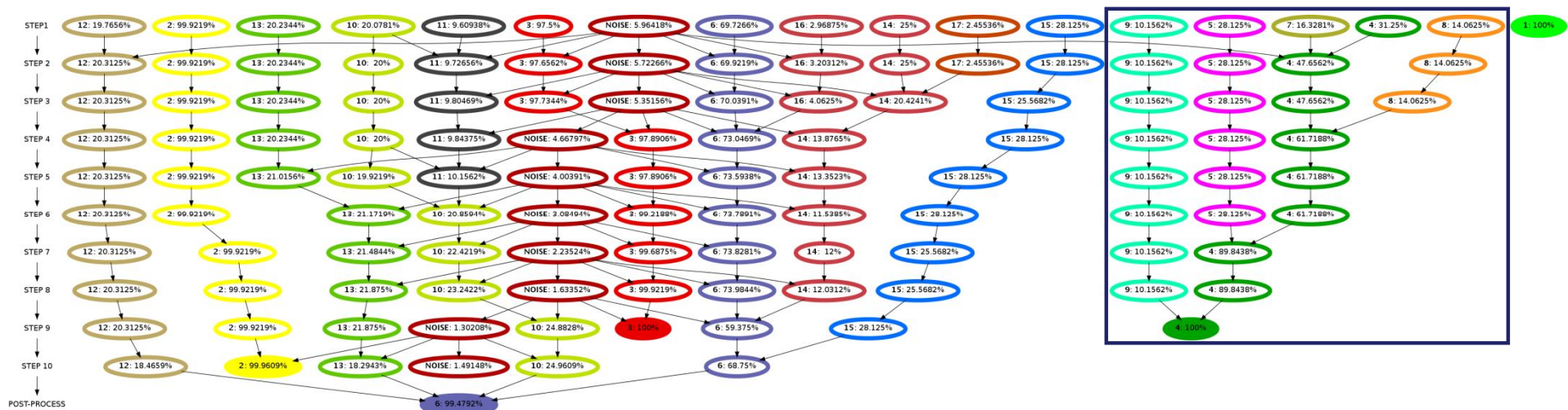
- ⌘ Analogy between DBSCAN and hierarchical clustering
 - Iterative bottom up construction of a *pseudo-dendrogram*
- ⌘ Cluster Sequence Score as target
 - Similar to X-means approach to decide *K-means* k parameter



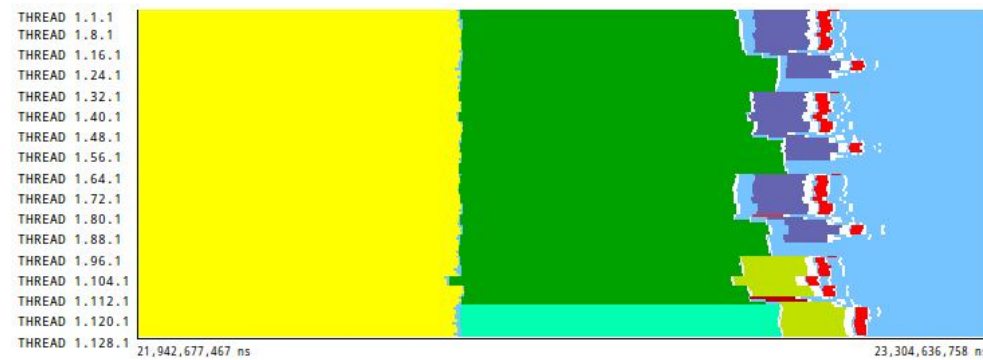
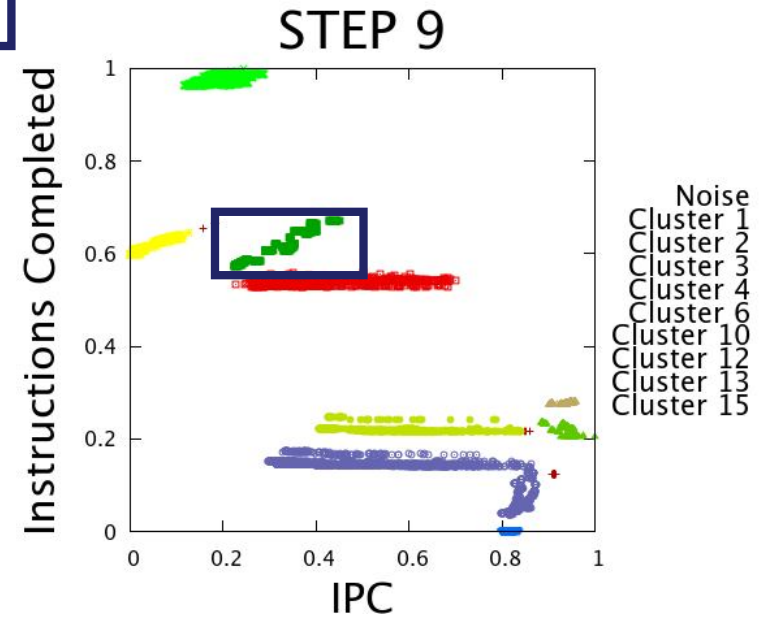
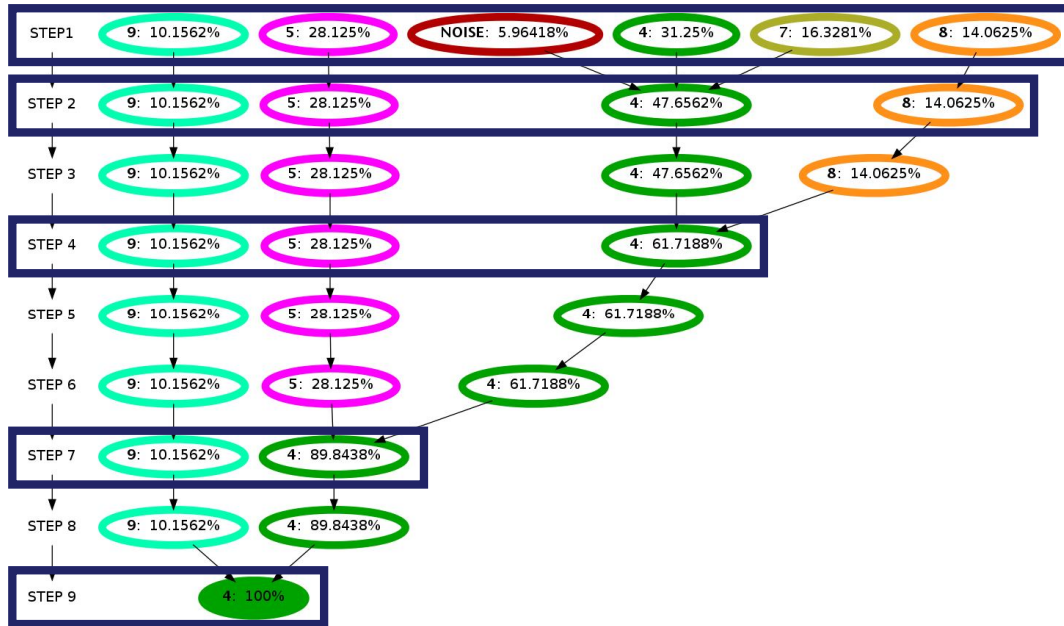
BT A 4 tasks



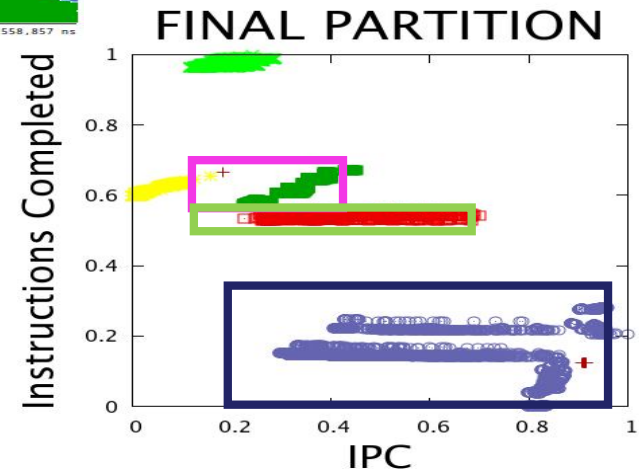
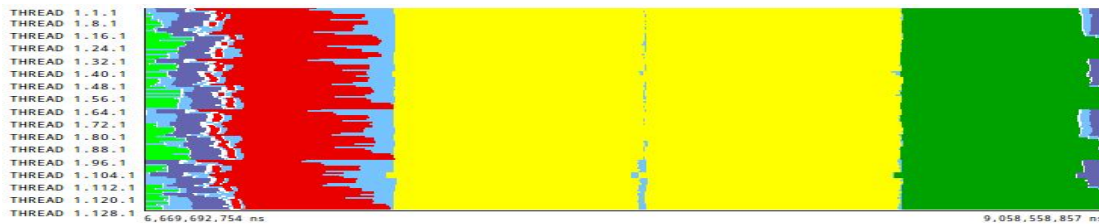
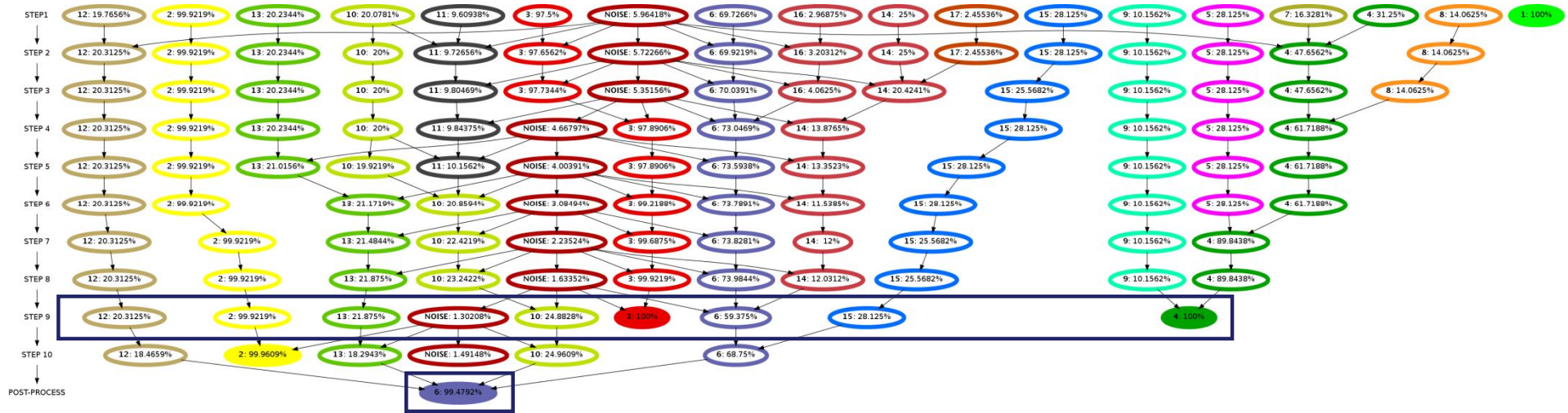
VAC4 128 tasks



VAC4 128 tasks



VAC4 128 tasks



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Correlating multiple runs

Use and correlate information from different runs

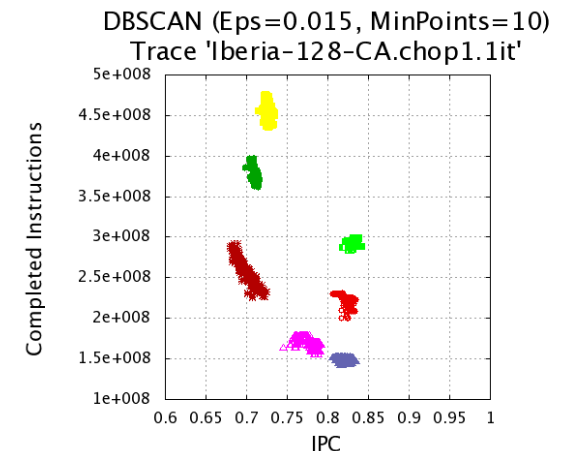
- Analysis of input parameters
- Code improvements
- Using different machines, compilers, flags, libraries
- Scalability studies
- Even for the same run: time evolution

Scatter plot = performance picture

- Identifies objects and their weight
- Correlation → image tracking

Based on heuristics

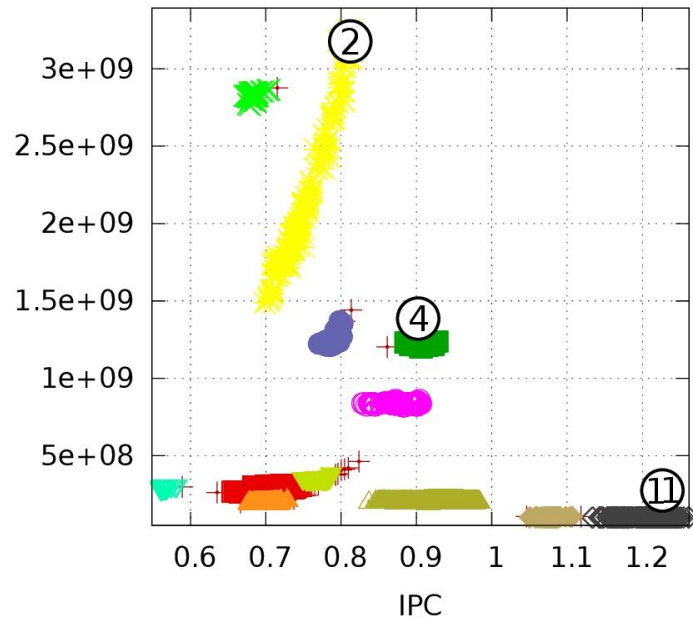
- Code regions evolve smoothly (things keep closer)
- No common callstack means not the same region
- Time sequence identify regions within and between runs



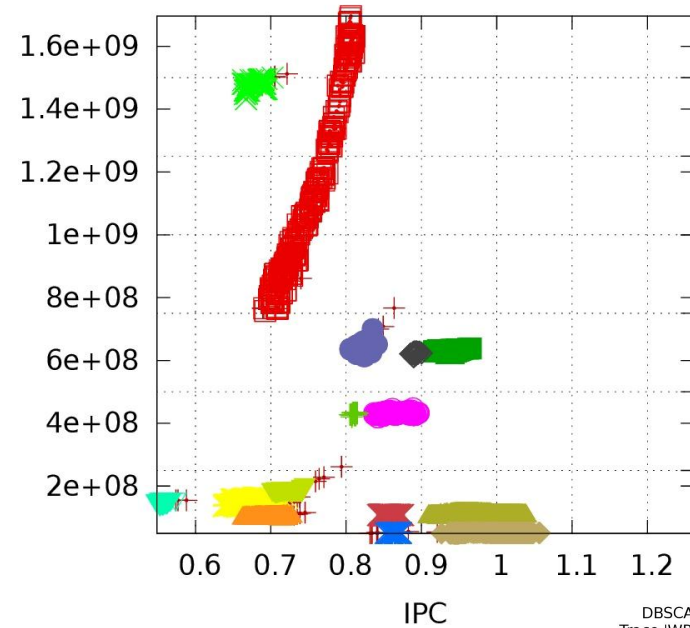
Scenario 1: Analysing scalability (WRF)

128 vs. 256

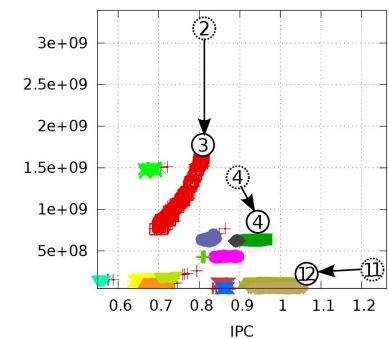
DBSCAN (Eps=0.018, MinPoints=10)
Trace 'WRF.MN.128p.chop2.clustered2.prv'



DBSCAN (Eps=0.018, MinPoints=10)
Trace 'WRF.MN.256p.chop2.clustered2.prv'

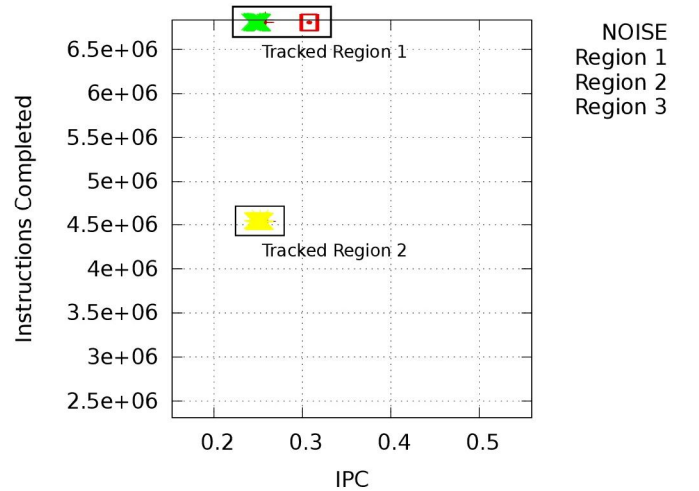


DBSCAN (Eps=0.018, MinPoints=10)
Trace 'WRF.MN.256p.chop2.clustered2.prv'

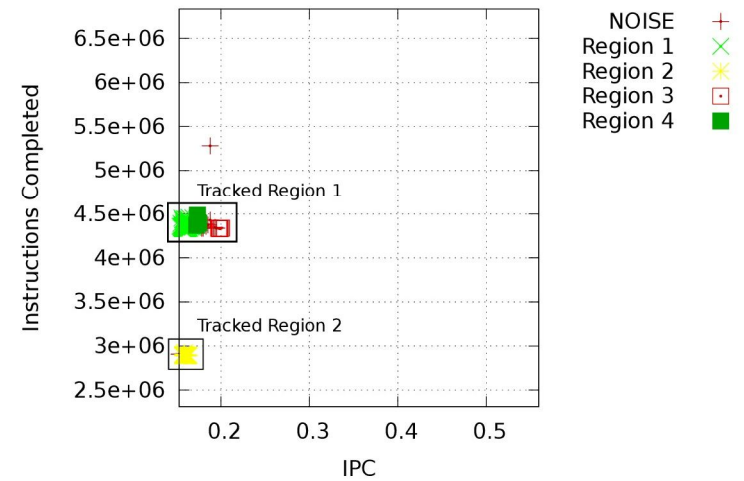


Scenario 2: Comparing machines & compilers (CG-POP)

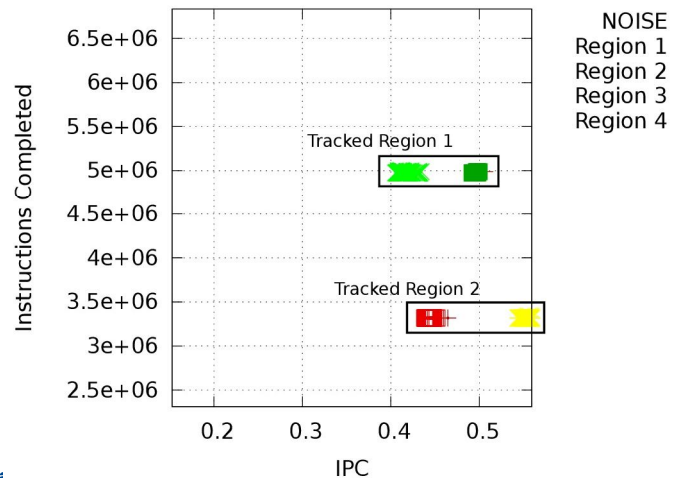
PowerPC, gfortran



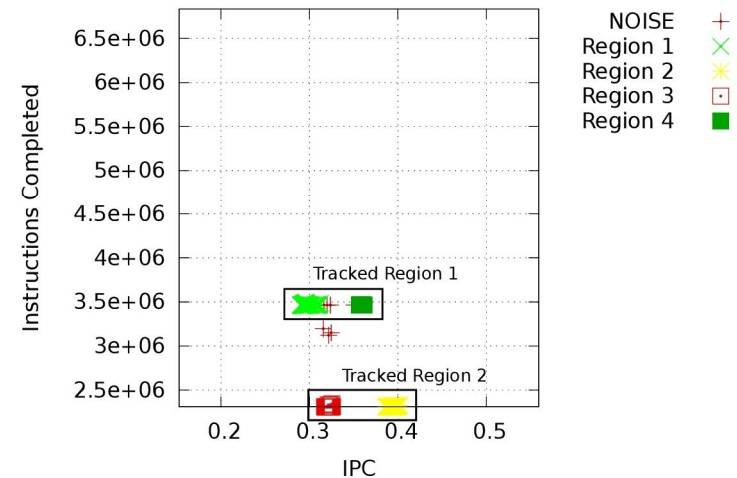
PowerPC, xlc



Intel, gfortran

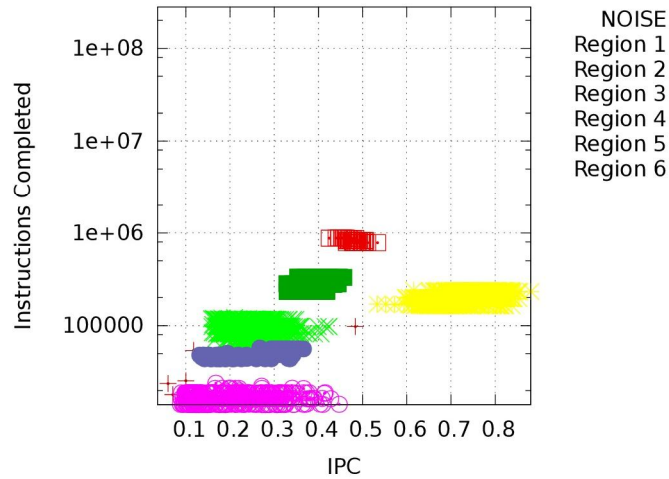


Intel, ifort

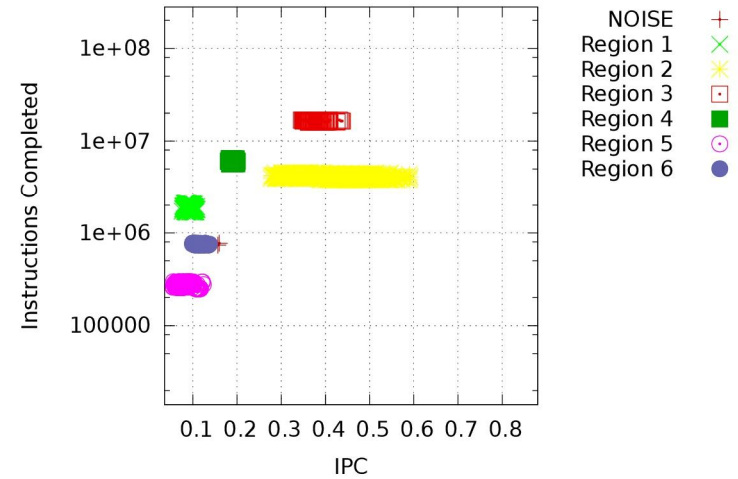


Scenario 3: Problem size impact (NAS-BT)

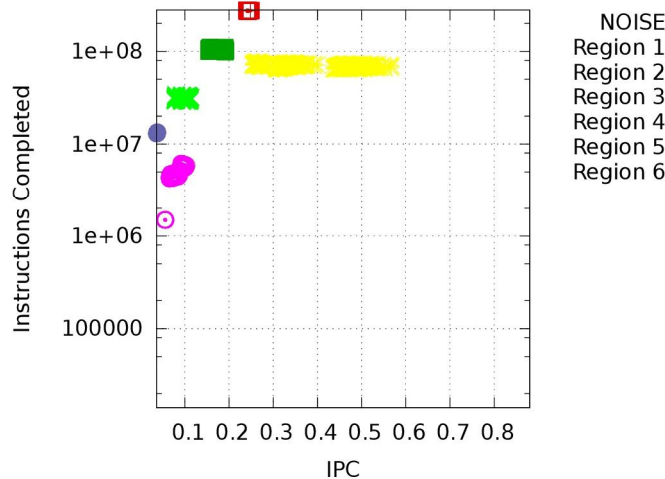
Class W



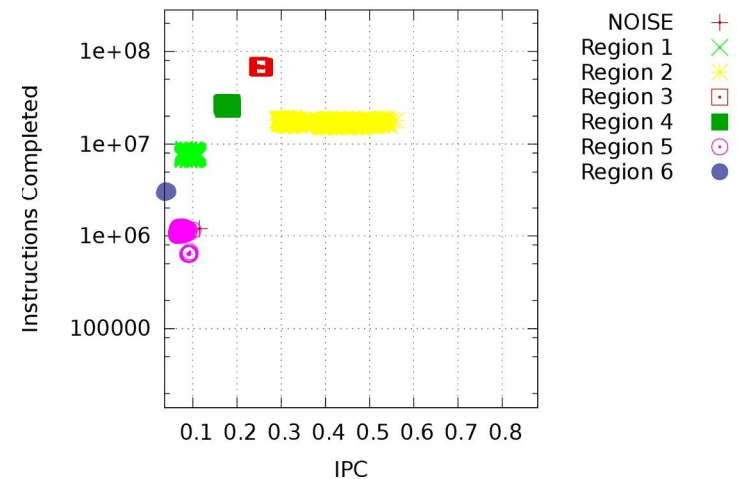
Class A



Class C



Class B



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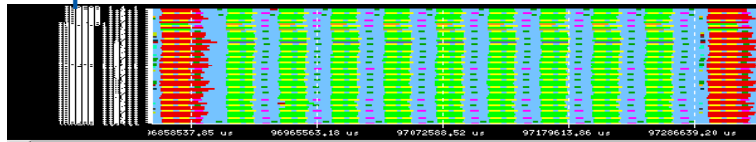
- Clustering + Folding

Sampling input data

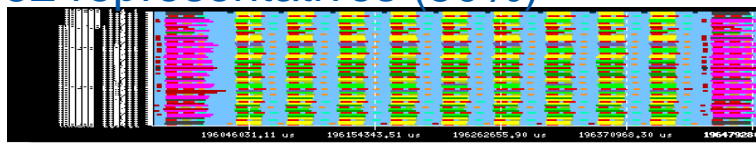
First target: online clustering

- Centralised approach (global clustering at the MRNet frontend)
- Data reduction through sampling
- Data classification based on the samples clustering

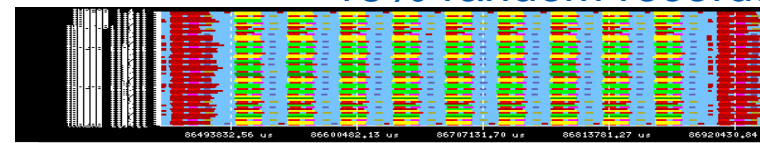
All processes



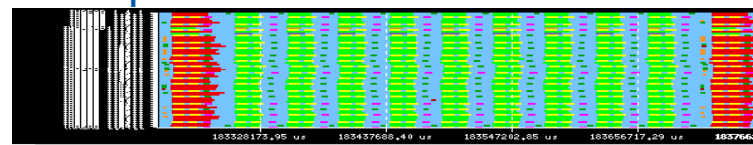
32 representatives (50%)



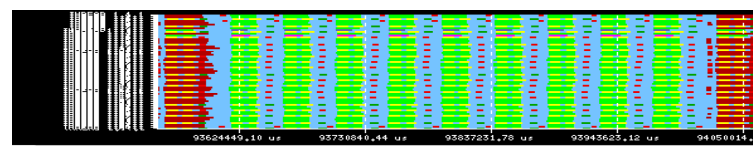
15% random records



8 representatives + 15% random



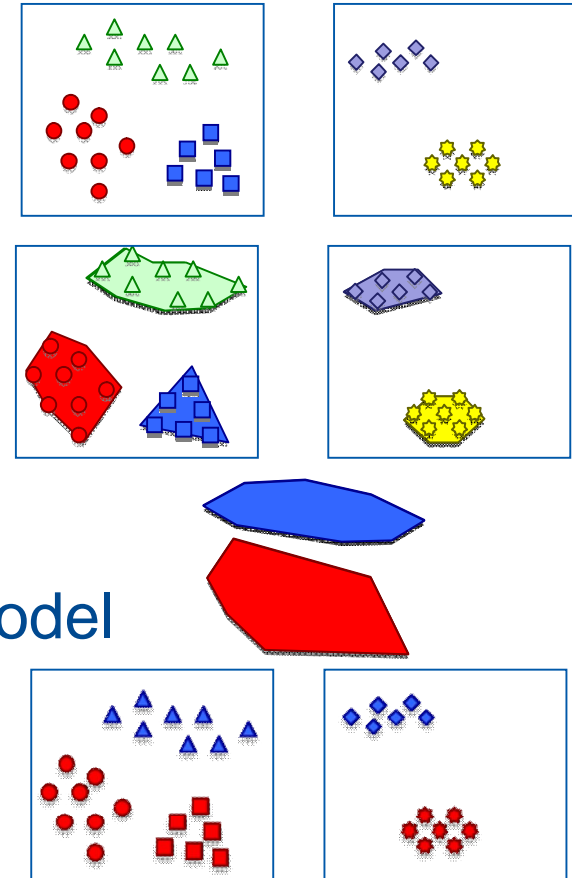
25% random records



75% less data
6s down from 2m

Hierarchical DBSCAN

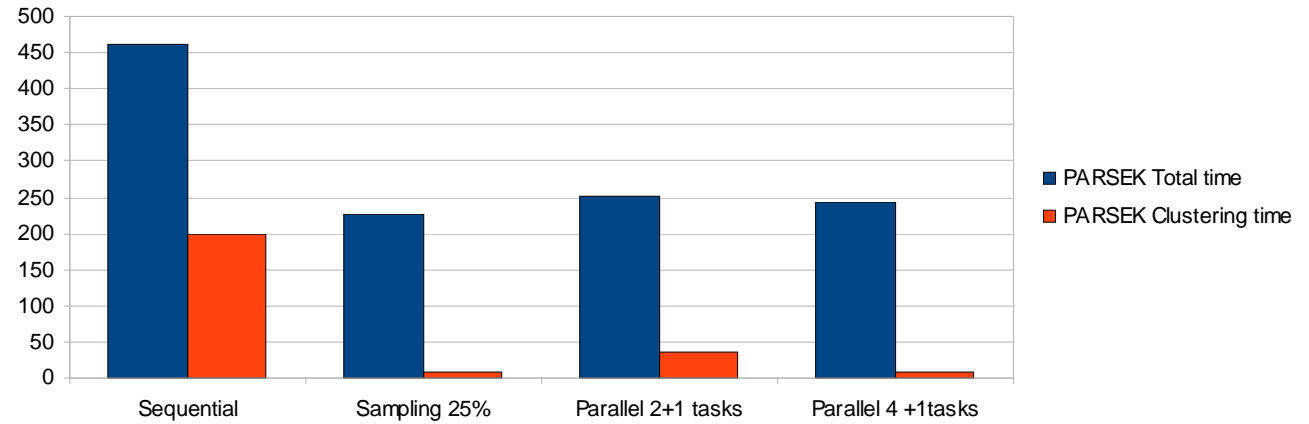
1. Local clustering
 - Up to 20-30k points per local process
2. Generate models
 - Convex hull, medial axis...
3. Merge the hulls over the MRNet
 - Intersect?
4. Broadcast the global model
5. Classify data locally using the global model
 - Point inside the hull?



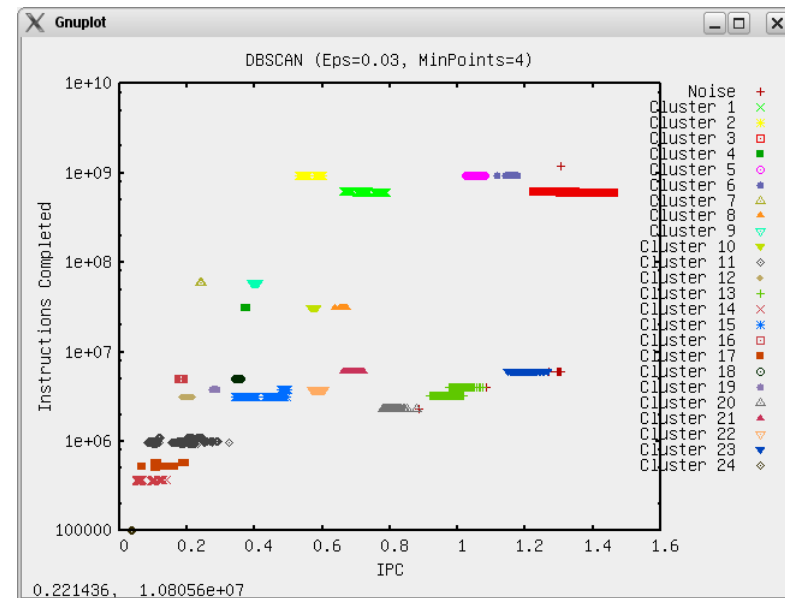
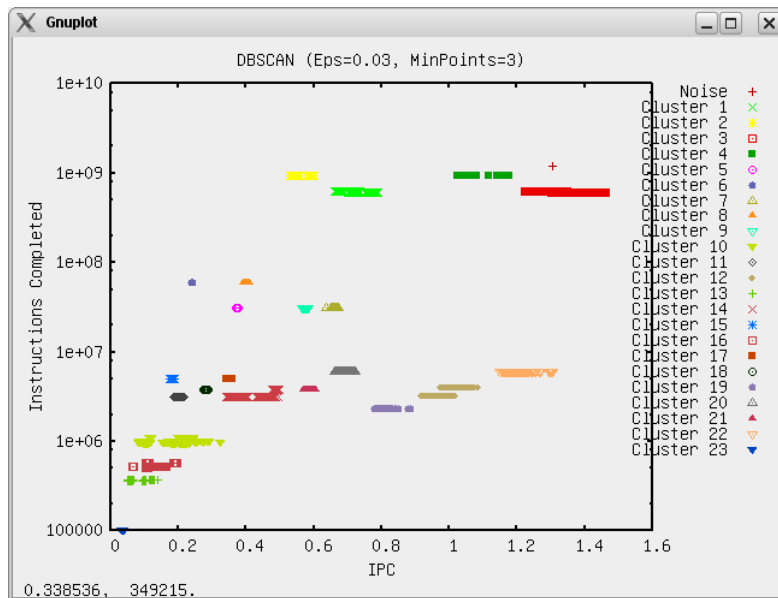
PEPC 4K tasks, 3095134 points, 273 tasks (16 way tree, 256 leaves, 12k points per local clustering) → clustering time 28.6 sec

Comparison (parsek)

31515 points

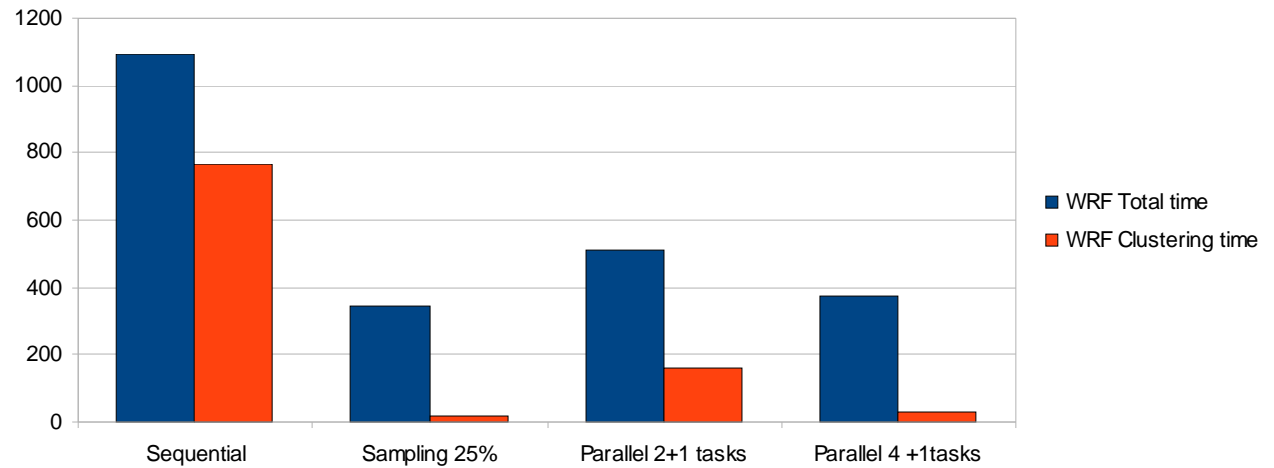


Sampling 25%



Comparison (WRF)

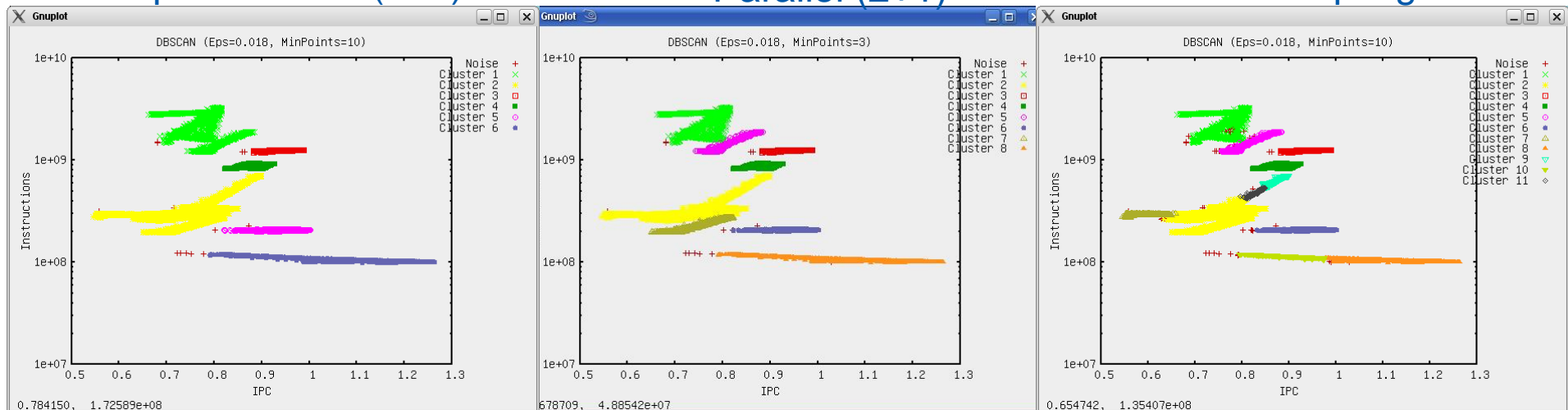
74240 points



Sequential /Par (4+1)

Parallel (2+1)

Sampling 25%



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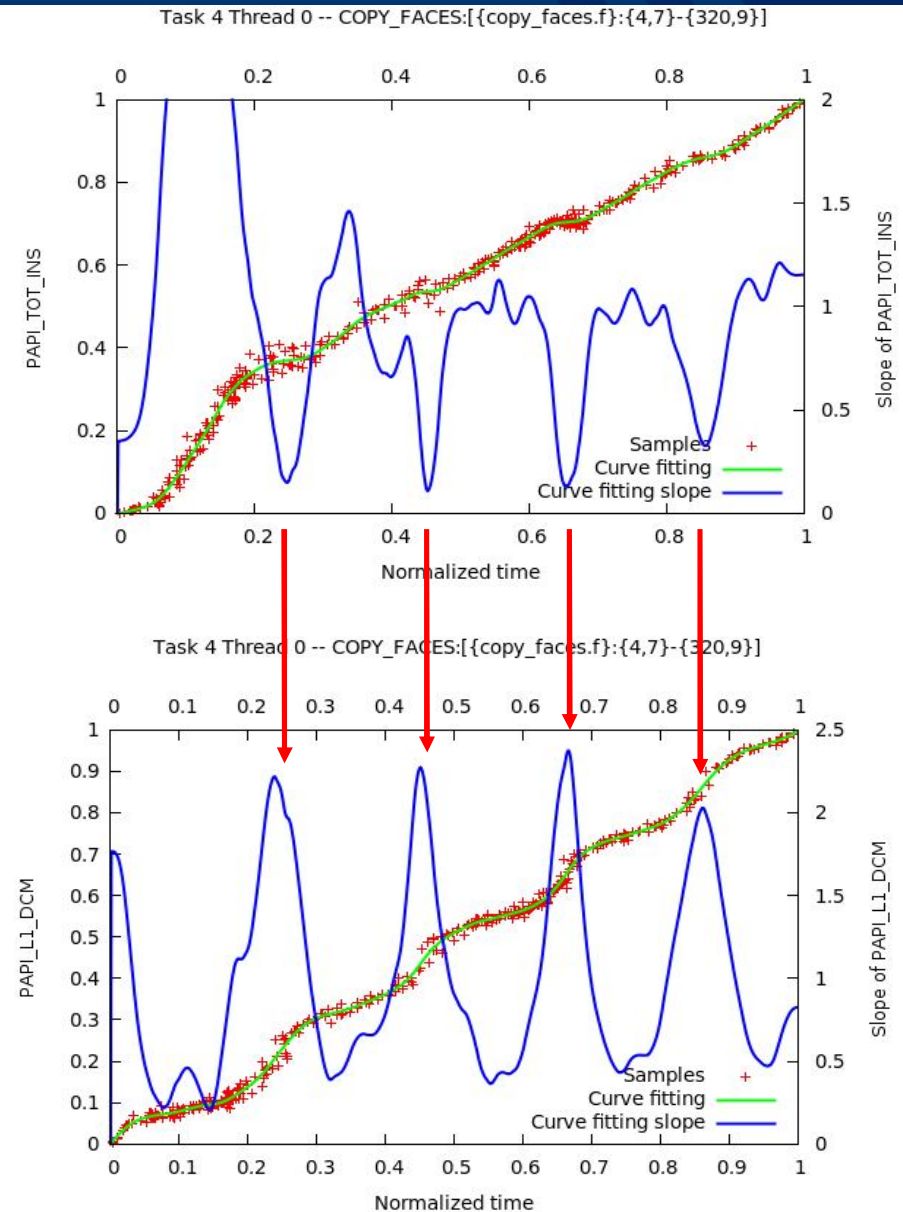
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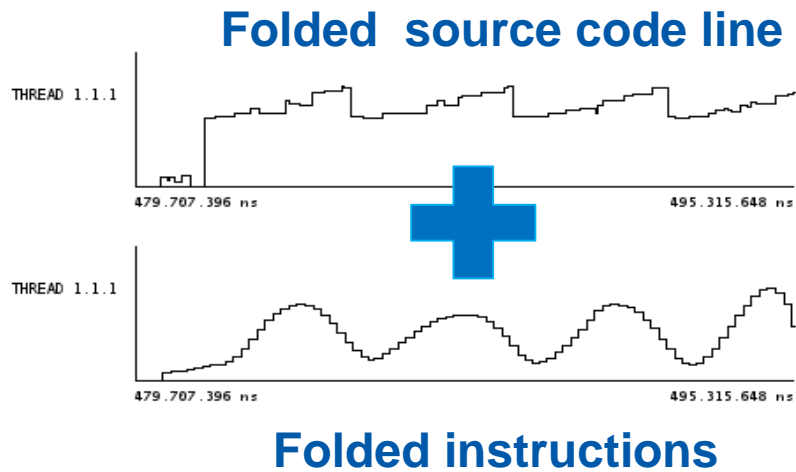
- **Clustering + Folding**

Can I get very detailed perf. data with low overhead?

- Application granularity vs. detailed granularity
 - Samples: hardware counters + callstack
- Folding: based on known structure: iterations, routines, clusters;
 - Project all samples into one instance
- Extremely detailed time evolution of hardware counts, rates and callstack with minimal overhead
 - Correlate many counters
 - Instantaneous CPI stack models



Correlating with sources: which line should I look?

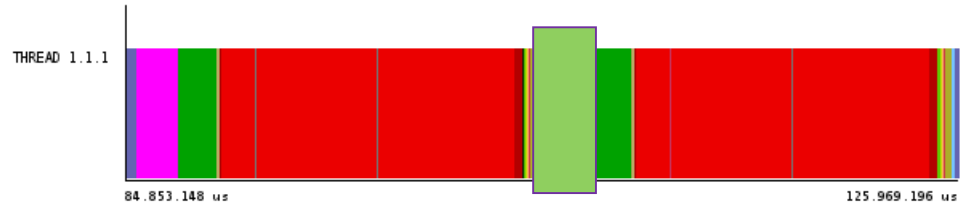
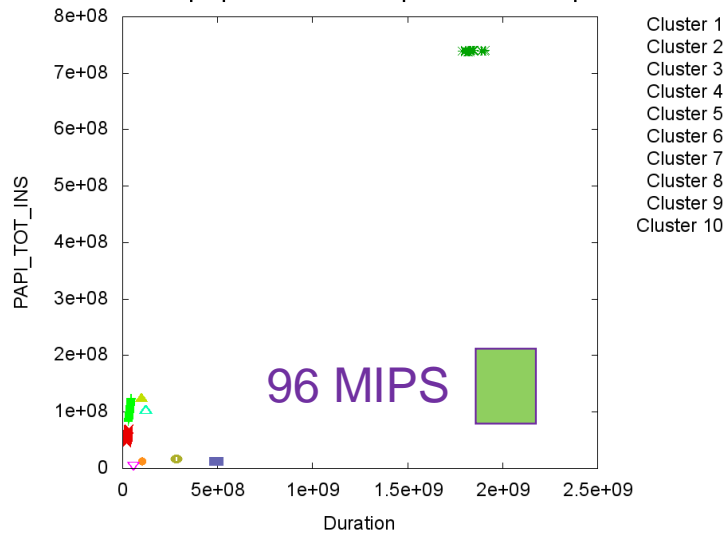


```
Etixer  Edita  Eines  Sintaxi  Buffers  Finestra  Ajuda
[Icons]
18 c-----
19 c  loop over all cells owned by this node
20 c-----
21 c  do c = 1, ncells
22
23 c-----
24 c  compute the reciprocal of density, and the kinetic energy,
25 c  and the speed of sound.
26 c-----
27       do k = -1, cell_size(3,c)
28         do j = -1, cell_size(2,c)
29           do i = -1, cell_size(1,c)
30             rho_inv = 1.0d0/u(1,j,k,c)
31             rho_i(i,j,k,c) = rho_inv
32             us(1,j,k,c) = u(2.1,j,k,c) * rho_inv
33             vs(1,j,k,c) = u(3.1,j,k,c) * rho_inv
34             ws(1,j,k,c) = u(4.1,j,k,c) * rho_inv
35             square(1,j,k,c) = 0.5d0 * (
36 >             u(2.1,j,k,c)*u(2.1,j,k,c) +
37 >             u(3.1,j,k,c)*u(3.1,j,k,c) +
38 >             u(4.1,j,k,c)*u(4.1,j,k,c) ) * rho_inv
39             qs(1,j,k,c) = square(1,j,k,c) * rho_inv
40           enddo
41         enddo
42       enddo
```

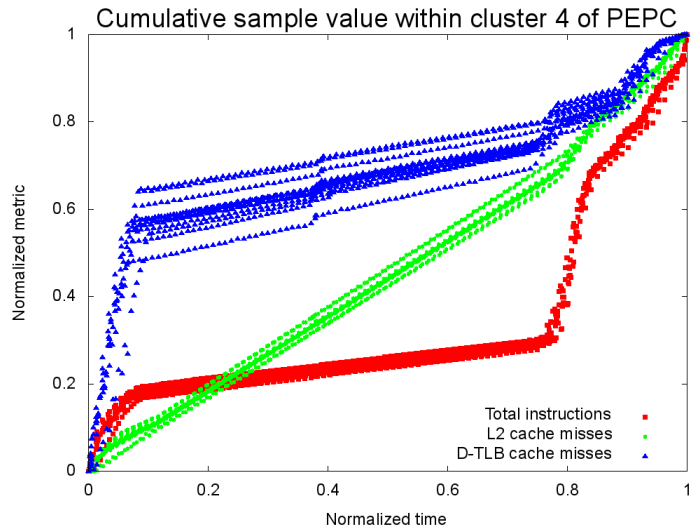
42.1 4%

The “benefits” of Fortran 90 intrinsic (PEPC)

DBSCAN (Eps=0.005, MinPoints=10)
Trace 'pepc.sorted.chop1.clustered.prv'



Performance metrics
16 MIPS
2.3 M L2 misses/s
0.1 M TLB misses/s



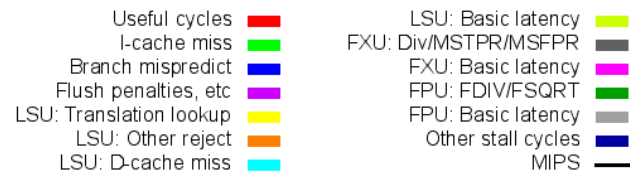
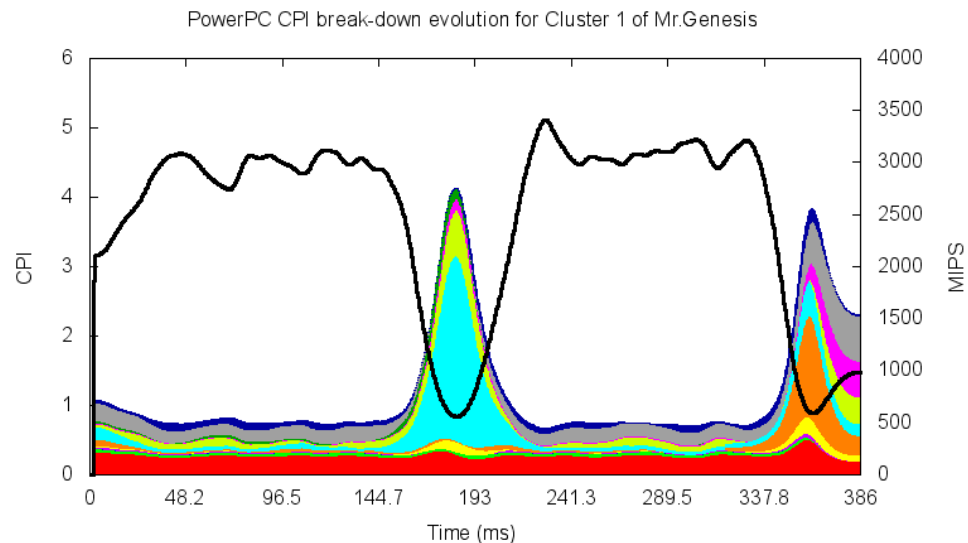
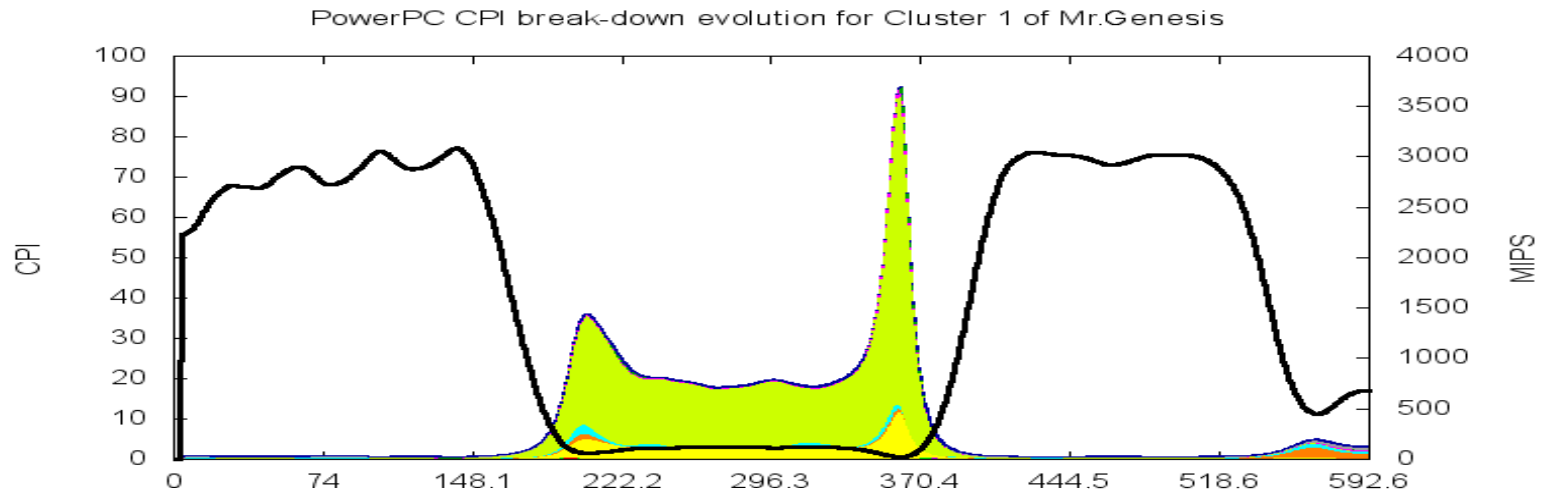
```
htable%node = 0
htable%key = 0
htable%link = -1
htable%leaves = 0
htable%childcode = 0
```



```
do i = 1, n
  htable(i)%node = 0
  htable(i)%key = 0
  htable(i)%link = -1
  htable(i)%leaves = 0
  htable(i)%childcode = 0
End do
```

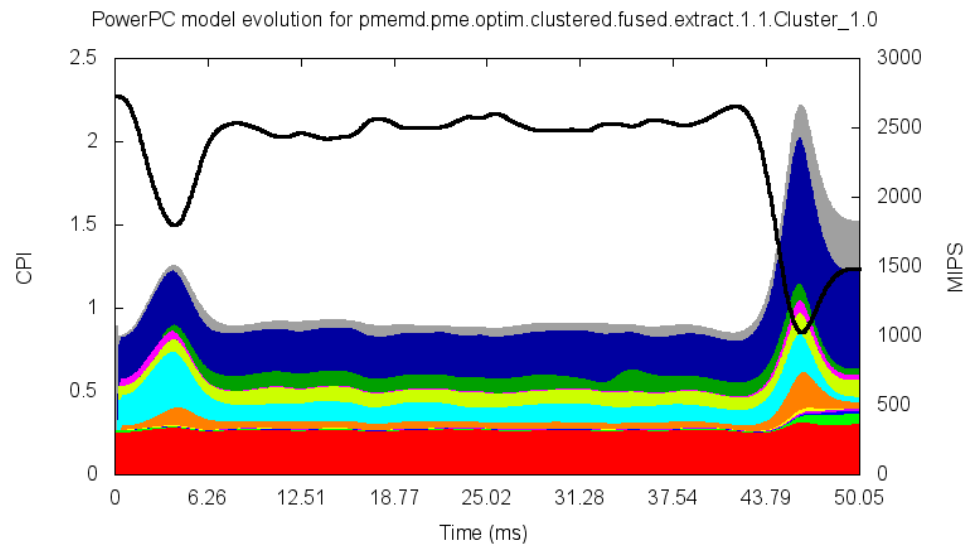
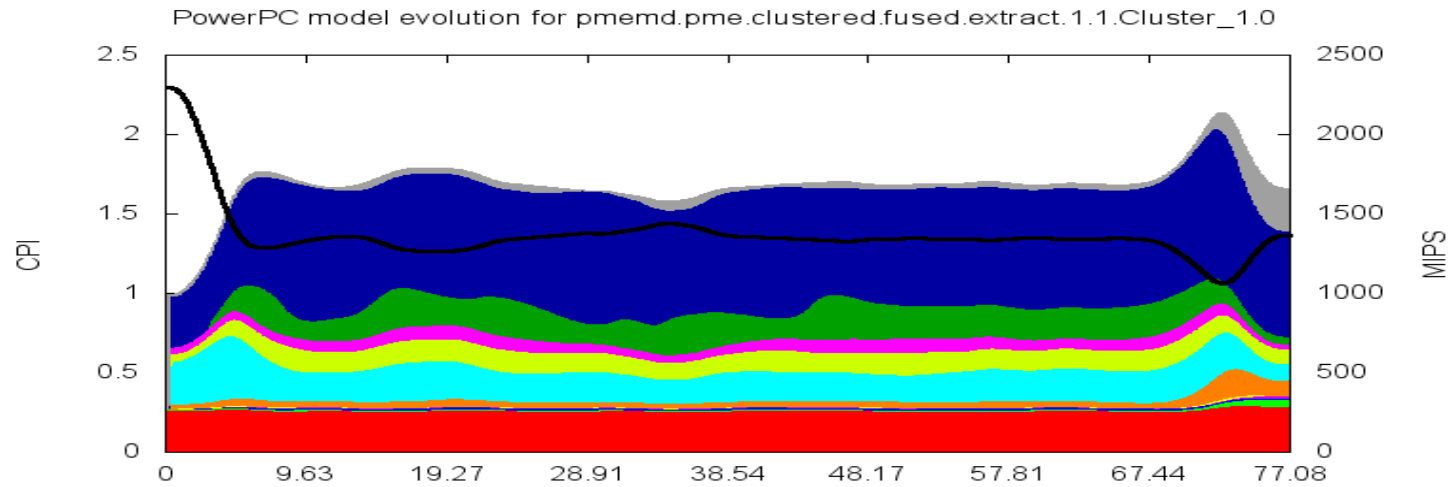
Changes
-70% time
-18% instructions
-63% L2 misses
-78% TLB misses
253 MIPS (+163%)

Interchanging loops (MR. GENESIS)



Framework for a Productive
Performance Optimization
(UPC-DAC-RR-2012-2)

Pre-computing float data – loop split (PMEMD)



- | | | | |
|-------------------------|---|----------------------|---|
| Useful cycles | ■ | LSU: Basic latency | ■ |
| I-cache miss | ■ | FXU: Div/MSTPR/MSFPR | ■ |
| Branch mispredict | ■ | FXU: Basic latency | ■ |
| Flush penalties, etc | ■ | FPU: FDIV/FSQRT | ■ |
| LSU: Translation lookup | ■ | FPU: Basic latency | ■ |
| LSU: Other reject | ■ | Other stall cycles | ■ |
| LSU: D-cache miss | ■ | MIPS | — |

Conclusions

⌘ Performance analytics

- Data analytics applied to raw performance data
- From data to insight
 - Information is on variability and distribution
- Huge room for research

⌘ Showed results of some techniques

- Clustering enables focusing the analysis and open many different uses on the analysis
- Folding makes possible to compute instantaneous performance metric functions with low overhead
- Tracking helps detecting movement in the performance space
 - Sequence of “frames” along many factors (not just time)